Search kit «OKO-2»

# **Operating Manual**



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# 2. DESCRIPTION OF DEVICE OPERATION

#### 2.1 Device designation

Search kit «OKO-2» is automated device and is designed for operative searching and detection dotted and extended metal and nonmetallic objects in various nonmetallic environments (ground, water, building designs and etc.)

#### 2.2 Device structure

The device is the monoblock. The monoblock consists of two changeable receiving and transmitting antenna units (BAPP), control, processing and indication unit (BUOI), folding handle rod (SSHR), off-line power supply unit (BP) and sets of cables (figure 2.2.1).



Figure 2.2.1. Complex with BAPP-II

#### 2.3 Arrangements of device operation

The SK operation is based on well-known radiolocation principals. The SK operation is based on ability of radio waves to be reflected from sections of environment boundaries with a different permittivity.

Short signal pulses are applied for subsurface radiolocation.

In order to form such pulses the excitation of the wideband transmitting antenna caused by the voltage swing is used. The direct processing of pulses of such small duration (hundreds picoseconds) is rather complex. So the stroboscope transformation method is used.

The control, processing and indication unit (BUOI) is to form and to transfer the instructions to the receiving unit of transmitting antenna unit (BAPP). Receiving unit is to form all the necessary signals of control for switching on the transmitter. The transmitting unit is to form the signals to the tested environment (cargo). The reflected signals are received by the receiving antenna unit BAPP, processed, and transferred to the BUOI.

The control, processing and indication unit is to form two-dimensional image of received signals and then are to display them on the indicator (screen) in the real time.

The special cable connection on BUOI, cable connect BUOI and computer by interface Ethernet is stipulated in the device for connecting with the external computer, and for forming three dimensional image.

## 2.4 Marking and sealing

The location of sealing wardrobe trunk, packing, BAPP I, BAPP II, BUOI and BP, are represented in the Appendix 1.

The seal of a wardrobe trunk is located on a long side part of wardrobe trunk, in the upper right corner.

#### 2.5 Description and operation of the device component

#### 2.5.1 The general

The main components of the device SK is the control, processing and indication unit (BUOI), receiving and transmitting antenna unit (BAPP) I and II range, and off-line power supply unit (BP).

Receiving and transmitting antenna unit (BAPP) is designed as a separate part, which is attached to one end of the folding handle rod. The off-line power supply unit (BP) is to attached to the second end of the folding handle rod. The control, processing and indication unit (BUOI) is attached in the middle part of the folding handle rod. Connection between the units is made using connecting cables.

Two changeable BAPP units: I and II range are used for operation in different frequency ranges. The length of folding handle rod in a fields status is 0,88 m, in operating position the length is (regarding on the height of a person) – up to 1,53 m.

The off-line power supply unit (BP 3,8/12) provides the non-stop work of the device for not less than 4 hours.

#### 2.5.2 Operation device of component parts

#### Receiving and transmitting antenna unit (BAPP)

Receiving and transmitting antenna unit functionally consists of receiving, transmitting units and receiving and transmitting antenna unit with volumetric damping resonator.

#### Receiving unit

The receiving unit functionally consists of receiving antenna unit, the scan stroboscopic device, selection and storage device (SD) and the control unit.

Reflecting from the inhomogeneity in the tested environment the signals are coming from input receiving antenna unit to output SD, where they are stored at the time of processing. The signals are coming from SD to the analog digital converter (ADC). The microprocessor receives the transferred digital signal. The control unit is to realize the preliminary processing of the received data and to transfer the data to the BUOI.

The signals for start of the transmitter are to form in the control unit and are to transfer to the transmitting unit.

The scan stroboscopic device is to form the pulses for the SD operation. The selection and storage unit is to remember the signal by control pulse and is to store it more than 1 micro second. It is enough time for ADC to transfer the processed analog signal to a digital code. BAPP II is to operate in the range, where the frequency ranges ADC are to allow the transformation of analog signals into the digital code without using SD. So for the range of BAPP I the signals from input of receiving antenna unit are coming to output of ADC.

The sensitivity of the receiving device is not worse than 300 microvolt.

#### Transmitting unit

The transmitting unit functionally consists of transmitting antenna unit, pulse shaper and high voltage-power supply unit. The pulse shape at receipt of the starting pulse are to form the (короткий перепад high voltage) which is to activate the transmitting antenna. The high voltage power supply unit is designed to transform the voltage of 12V into power which is necessary for operation the pulse shaper. (duration of a pulse of 1,5-2,2 nanoseconds with fronts up to 0,2-0,3 nanoseconds and frequency of following 200 KHz.)

#### The control, processing and indication unit (BUOI)

The control, processing and indication unit is based on the digital signal processor and functionally consists of all climatic liquid crystal indicator, the control device and the keyboard. All operations are realized using the buttons located on the front panel. Using the buttons the operator is to choose the required points or parameters in menu which are displayed on the indicator and is to change them according with the required task.

According with the choice of the mode and parameters, the control device is designed on the signal processor, forms instructions and transfers them to the antenna unit (BAPP) using interface RS-485.

The accepted data are processed and displayed on the screen.

BUOI has the high definition (640x480 points) liquid crystal color display.

BUOI allows to keep the received data in the memory 1Gb (this size of memory is sufficient for storage approximately 240000 paths), that at the step of scanning 5 cm is about 12000 m of a continuous profile

The data from BUOI can be copied on a personal computer on interface Ethernet. The transferring order is described in the User's manual.

The further data processing can be made on a personal computer using Geascan32 software (see. The User s guide program Geoscan32).

#### Autonomous power supply unit (BP)

The autonomous power supply unit (BP) consists of ten Ni-Mh accumulators and the accumulator indicator of the category, which is control and indicate of the accumulator battery. BP 3,8/12 is equipped with self-recovering fuse. The voltage is supply from BP to the BUOI and BAPP using power supply cable.

# 3. WORK WITH THE DEVICE

#### 3.1 Assembly of the device

1. Take from wardrobe trunk SSHP, BP, BUOI, BAPP I/II, cable BP and cable BAPP;

2. Choose the required BAPP according with the depth of search. At depth up to 1 m - BAPP II, from 1 up to 3 m – BAPP I;

3. Fix BAPP on the foldable handle rod in such away that spring-force fixing ledge of foldable handle rod is to be correspond to the socket of the supporting element on the BAPP case (figure 3.1.1);



Figure 3.1.1. BAPP Supporting to the folding handle rod.

4. Rotating clock-wise twist completely charged off-line power supply (BP) unit on the folding handle rod (figure 3.1.2);



Figure 3.1.2. BAPP Supporting to the folding handle rod.

5. Connect connectors X2 and X3 of folding handle rod with cable of off-line power supply unit (cable marking «Cab. BP»);

6. Connect connectors X1 BAPP and X1 of folding handle rod by antenna cable unit (cable marking «Cab. BAPP»);

7. Fix the BUOI on the folding handle rod. For that turn clock-wise the fixing arm of BOUI and fix it in this position, insert guiding connector, to the corresponding parts of the guide supporting element SSHR and then return a fixing arm of BOUI in a starting position (figure 3.1.3);



Figure 3.1.3. Support BUOI on folding handle rod.

8. Rotating clock-wise (if looking clockwise from the side of the supporting element of BUOI) release the socket joint fixing the location of a folding handle rod (figure 3.1.3) and pulling the telescopic of a folding handle rod up to the required value, adjust the length of a f.b.h. (regarding the standing height of a person), then rotating counterclockwise (if looking from the side of a supporting element of BOUI) tighten the fixing socket joint;

9. Releasing the screw which fixes the turn of BUOI movement, adjust the turn angle of BUOI in a relation to a handle rod (figure 3.1.3);

10. On releasing the srew fixing the turn angle of BAPP, adjust the angle of slope of antenna unit in relation to a handle rod (figure 3.1.1).

## 3.2 The device in operating position.

The device is to be in the hand in the position that are shown on the figure 3.2.1 It is necessary to chose the length of the shoulder belt that the major part of weight SK «Oko-2» will be on the belt and at the same time the freedom of moving SK is provided (figure 3.2.2)

BAPP is to be directed at the side of the scanning environment (rejection +\_ 20 C from geometrical axis BAPP) and is to be moved in a parallel surface of cargo, close by or with a slight detachment (up to 0.1 m) from cargo.



Figure 3.2.1. The position of the device in the hands



Figure 3.2.2. Device in operating position

## 3.3 Preparation for scanning

1. Press the key on BP case for switching on the power supply of the device. At that time the Led indicator is to flash at the BP case and after several seconds of automatically SK testing and short-time message «Ready», on the BUOI screen is to display operation mode select menu of device (figure 3.3.1) current voltage of power supply unit and time. The points of menu are to choose by pressing of functional buttons on the opposite corresponding name functions in the dark rectangulars in the right part of screen BUOI.



Figure 3.3.1. A device operation mode selection menu

2. Press functional key «2» («Search»). The type of connected BAPP is defined automatically.

After the «Search» mode, the signals are to be displayed on the BUOI. These signals are reflected from the objects and layers of the scanning zone in the way of black and white lines of various brightness (colored lines) (figure 3.3.2). The wave picture of current written set of the reflected signals of the selected record time range (as so-called lines of signal) is at the left side of the screen. At that time Led indicator on the BAPP case is to be continuously lightning that is to identify the operation of the transmitting unit of the device.



Figure 3.3.2. Display of written down signals

The first three half-periods of each line (on the figure 3.3.2 is allocate by a dotted frame in the image of wave form) as so called the signal of direct transmitting. The signal of direct transmitting is not to go to the scanning zone, it is to go directly – from transmitting antenna unit to the receiving and as a rule, it has the biggest amplitude in the current line. The top area of noise is above the signal of direct transmitting. The normal position of the signal of direct transmitting – figure 3.3.2.

If after switching on the device, the picture signal of the direct transmitting is below normal position, using the following buttons " $\uparrow$ "  $\mu$  " $\downarrow$ " it is necessary to modify its position.

By the buttons « $\leftrightarrow$ » и « $\rightarrow$ » it is possible to change the contrast of radarogram (For additional information use the program GeoScan32 Users manual).

## 3.4 Set parameters of scanning

1. Press the key "Esc" to select the measurements mode menu (figure 3.4.1)



#### Figure 3.4.1. Measurements mode menu

2. Press the functional key «4» («Parameters») to select the options menu of parameter measurements settings. (figure 3.4.2).



Figure 3.4.2. Menu of parameter measurements settings.

3. Press the functional key «2» («Epsilon\*10», figure 3.4.2) to activate the options of environment dielectric permeability and with the following buttons " $\uparrow$ " and " $\downarrow$ " and to fix the required value of dielectric permeability. The value of dielectric permeability multiplied x10 is displayed on the screen for display convenience of a fractional part of dielectric permeability. This value is used for calculation of a depth scale during the signals processing. Table on the screen helps to choose value of dielectric permeability for some environments (figure 3.4.2).

4. Press the functional key «3» («Time range», figure 3.4.2) to activate the options of the depth scanning (time range of the signals record) of the environment and with the buttons " $\uparrow$ "  $\mu$  " $\downarrow$ " install the required value.

5. Press functional key «4» («Accumulat.», figure 3.4.2) to activate the mode of the accumulate signals from antenna. Use " $\uparrow$ "  $\mu$  " $\downarrow$ " buttons for changing this value. Big value of this parameter increases depth of sensing, but reduces to decrease in speed of scanning.

Recommend values of Accumulate:

1-4 – fast mode of scanning;

8-32 – basic mode of scanning.

6. Press the functional key «5» («Delay», figure 3.4.2) to activate the options of a discrete regulation signal shift of a direct transmitting to the top profile (smooth regulation of a shift is made with the help of the following buttons " $\uparrow$ "  $\mu$  " $\downarrow$ " in a «Search» mode) and by the pointers " $\uparrow$ "  $\mu$  " $\downarrow$ " fix the required value.

7. Press functional key «6» («Mode», figure 3.4.2). Menu «Mode» (figure 3.4.3) provide for select the measurements mode of scanning.

- Continues information about distance doesn't record.
- By steps each trace record by pressing «Enter»
- Wheel If in the device modification stipulated the operation with a moving sensing transducer (wheel) during work operation in the mode«Wheel», the lines are only recorded through the distance of a given step (can't use with BAPP1, BAPP2).
- «Wheel opt.» It is necessary to check up the established parameters of the used moving sensing transducer with the help of the menu «Wheel opt» when you use the given mode.
- 8. Press the functional key  $((\uparrow))$  to return to the menu of parameter measurements settings.



Figure 3.4.3. Mode processing menu

# 3.5 The operation of scanning

1. Set the antenna power supply unit on the surface which is to scan and press the functional button «2» («Record», figure 3.5.1) for the record of a profile.



Figure 3.5.1. Measurements mode menu

2. Smoothly move the antenna power supply unit on the planned trajectory. The search of the deep objects is possible to make at the mode, that is similar to the operation with metal detectors and mine detectors (figure 3.5.2). Antenna unit is possible to take of from a ground surface on a distance 5-10 sm. It doest influence on the detection characteristics. The device in equal intervals will radiate impulses and accept signals from the moving antenna unit of the device, that are reflected from inhomogeneities of the scanning environment. The wave picture of the profile (radogramma) will be displayed on the BUOI screen while the device will be moving. The reflection of point objects is displayed on the radogramma as hyperbola (a vertex of hyperbole is to correspond to the nearest point of objects of the antenna unit), reflection from the objects and layers are represented in tended horizontal lines (figure 3.5.3).



Figure 3.5.2. The moving trajectory of BAPP in searching of the dug objects



Figure 3.5.3 The examples of radogramm of detection objects

3. Press button «5» during recording for drawing label. Drawing the label accompany by sound signal. Program assign labels serial number.

4. Press «Esc» for save file and «Enter» for approval of saving (figure 3.5.4).



Figure 3.5.4. Saving file

5. The «Store» button allows to save a file with information from screen of BUOI.

#### 3.6 Detection of movement

The mode intend for detecting the moving object in real time. Press the functional key «3» in main menu of BUOI («Det. move», figure 3.4.1) to activate the mode. Select item «Param det» (button «5», figure 3.6.1).



**Figure 3.6.1.** The detection of movement mode

Numerical value of parameter "Param det." is to define the quantity of the lines for averaging and changes by the pointers " $\uparrow$ "  $\mu$  " $\downarrow$ ". If the value «1» is installed, the processing is not performed, if the value more than 1, the set quantity of the lines is to average and the averaged lines is to subtract from the again accepted lines. For example, this mode can be useful during the detection of the moving objects behind the wall and so on.

<u>Recommendation:</u> Param.det = 50; Accumulate = 8;

Recording and saving files in this mode make in compliance with section "3.5. The operation of scanning".

The main condition for the moving objects detection is to fix the antenna unit on the wall through which the scanning of the adjoining room is made or to fix it on the floor for detection the objects that are below, on the previous floor-level. On the figure 3.6.2 there is a scheme detection of a moving person in the concrete tunnel. On the figure 3.6.3 there is a detection radogramm of the moving person in the concrete tunnel.



Figure 3.6.2. A scheme detection of a moving person in the concrete tunnel.



Figure 3.6.3. Detection radogramm of the moving person in the concrete tunnel

For detection the moving objects through the wall it is necessary to fix the antenna unit on the wall, do not try to keep the unit by hands, it can make the detection of the moving objects complicated. On the Figure 3.6.4 there is the detection radogramm of the moving animal (dog). The scanning was made through the brick wall of the adjoining room, the thickness is 40 cm.



Figure.3.6.4. The detection radogramm of the moving animal (dog) that is scanning through the brick wall

It is necessary to perform the following recommendations during search work:

1. The device should move along the trajectory planned by operator closely or with distance (up to 0,1 m) from the surface of the scanning environment.

2. The speed of the antenna block moving should be no more than 1 km/s while you are scanning the complex surfaces on the relief. The antenna unit should contact the scanning surface.

3. For further construction three-dimensional image in the program GeoScan32 write down not less than 7 parallel profiles (for more details see Users guide of the program GeoScan32).

4. Remove BAPP from the folding handle rod for scanning in the places with difficult access and use the cable with the 5 meters length, perform the operations by two operators.

5. Press the functional key "Esc" at the final point of a trajectory, thus there will be «Mode Menu of measurements» (Figure 2.8). Press a function key «3» «Save » to save all the dates on a hard disk of BUOI. On the BUOI screen will appear the window with the number of a kept file, press twice the fictional key Enter to confirm the keeping.

Press the functional key «2» for recording the following profile («Profile», Figure 2.8).

To input in the main choice menu of an operation mode press the functional key «5» («Output»,Figure. 2.8). The light-emitting diode (LED) indicator on the BAPP case will not flash, it means that the transmitting unit of the device will be switched on.

# 3.8 Functioning of "Start-Stop" button.

Start-Stop" button (figure 3.1.3) is for the on-line control of the start and end of the signal recording, putting marks (tags) during recording and it functions in the following way:

Short-term pressing of Start-Stop" button signals the start of signal recording ("Record" mode is switched on).

Short-term pressing of Start-Stop" button while signals recording helps to put marks (tags) on the profile. The marks serve for the additional referencing of the profile to the location.

Long pressing (about 2 sec.) of Start-Stop button while signals recording terminates the profile recording and stores a profile file to the power supply independent memory unit of BUOI.

## 3.9 Device Switching off and Disassembling.

To switch off the device press only once the button on the case of PSU (power supply unit) to switch off the power supply (wherein the LED indicator on PSU goes out).

After switching off SK the device must be disassembled (in the order opposite to assembling order) and packed in transportation bag according to the scheme of packing.

#### 3.10 Viewing files

Pressing a"4" functional key in the menu of device operation mode selection («File», figure 3.3.1) select an operation mode "File."

In opening operation mode menu a list of files of profiles with extension \*.GPR stored in a hard drive of BUOI is displayed. (Figure 3.10.1).

Open Capacity: 1047552 Kb Free: 1002752 Kb Files: 27	A         PR0002.GPR           A         PR0003.GPR           A         PR0005.GPR           A         PR0006.GPR           A         PR0008.GPR           A         PR0009.GPR           A         PR0003.GPR           A         PR0010.GPR           A         PR011.GPR           A         PR012.GPR           A         PR013.GPR           A         PR014.GPR           A         PR015.GPR           A         PR015.GPR           A         PR016.GPR           A         PR019.GPR           A         PR019.GPR           A         PR022.GPR           A         PR022.GPR		1 2 3 4 5	Esc (
Enter-Open, Es	z-Nenu	17:16		E.

Figure 3.10.1. Menu list of the stored files.

To open a file use " $\uparrow$ "  $\mu$  " $\downarrow$ " keys to chose a required file and press an Enter button. If you press Esc now, a menu for work with files will appear on the screen (figure 3.10.2), which eanables either to delete this file or to delete all files, or to format a hard drive of BUOI.

Warning! BUOI hard drive formatting deletes all files on it! Formatting is to be used only for correcting errors in file system of BUOI.

File Carl	Ene
	ESC
	$\frown$
Remove	
	48
Remove All	
	79
Format	
Frit	and the second second
	Entor
	Enter
6	
F F F F F F F F F F F F F F F F F F F	-
	Remove All 2 Romat 4 Exit 5 6

Figure 3.10.2 Menu of files operation

Press the key «Enter» («Open») to open the selected file, the name of the file is displayed at the left corner of the screen. After the file is opened, press the button "Esc" (figure 3.10.3) the menu of the processing file are selected, where become accessible the options of the processing «Processing», «View» and «Contract» (figure 3.10.4).



Figure 3.10.3. Menu of the fail processing list

Press the functional button «2» (figure 3.10.3) and the options of processing files «Amplication», «Subtraction», «Filter» become accessible (figure 3.10.4). Assignment and necessity of application of each kind of processing is represented in User's manual of the program GeoScan32.



Figure 3.10.4. File processing menu

«View» button give an access to a menu for handling with a display of radarogramm on a screen of BUOI (figure 3.10.5)

Press a "2" functional key («1:1» (figure 3.10.5) and then a Esc key a mode «1:1» is activated. At that if the file size is less than a screen size, then a radarogramm takes only part of a screen ; if the file size is more than a screen size, then only that part of a radarogramm that will have space on the screen will display on a screen of BUOI. If the file size is more than a screen size than the keys « $\leftarrow$ » and « $\rightarrow$ » enable to move a displayed part of the image.

Press a "3" functional key («Whole file»(figure 3.10.5)),and then an Esc key a radarogramm is scaled that it could have space on a screen of BUOI.

Press a "4" functional key («Sight rod», (Figure 3.10.5)), and then an Esc key, the oscillogramm corresponding to a signal of direct transmission and reflected signals (figure 3.10.6) is displayed. Keys « $\leftarrow$ » and « $\rightarrow$ » enable to move the oscillogramm on the file to the left or to the right , and keys « $\uparrow$ » or « $\downarrow$ » enable to move up or down on the sight rod, while amplitude of the current point is being displayed in the upper left corner of the sight rod window.

Press a "4" functional key («Contrast», figure 3.10.3) activates a mode of contrast ratio of a radarogramm and " $\uparrow$ " & " $\downarrow$ " keys install a required value.



Figure 3.10.5. Menu "View"



Figure 3.10.6. The view of sighting

#### 3.11 Settings

Press a "4" functional key in a menu of a device operation mode ("Settings", figure 3.3.1) select an operation mode "Settings".

In an open menu of a Settings mode items of "Palette", "Time", and "Test. key" are displayed.

#### 3.11.1 Palette

Press a "2" functional key " Palette" (figure 2.11.1) displays a list of a colors palette files (palette files can be recorded with the help of a GeoScan 32 program) and a sample of the palette colors (blue color) for a file selected

Capacity: <u>MCS1.CS</u> 1047552 Kb <u>MCS2.CS</u> Free: <u>MCS3.CS</u> 1001088 Kb <u>MCS4.CS</u> MCS5.CS Files: 5	
Files: 5	
1_Gran Fater_Annly Fac_Fuit	00.08

Figure 3.11.1. List of colors palette

By " $\uparrow$ " & " $\downarrow$ " keys select a file with a required color palette. Black- and white palette is selected by a "1" functional key. Press an Enter key enables to activate a selected palette for representation of profiles.

#### 3.11.2 Time settings

Press a "3" functional key 'Time" enables to activate a menu of date and time settings (figure 3.11.2).

Date and time setting Date Time 28.10.06 Date 28 + Hour 11 +			
Date         Time           28.10.06         11:44:20           Date         28	ette	Palet	Date and tim
	ie	Time           11:44:20           Hour 11	Date 28.10.06 Date 28
Month 10 + Year 6 + Sec. 0 + Test.	t. Key	<ul> <li>▲ Min. 45 ★</li> <li>▲ Sec. 0 ★</li> </ul>	Month 10 Year 6

Figure 3.11.2. Date and time settings

To set up date and time one should set up date and time in corresponding items from which the timer will start counting out.

Item selection is made by " $\leftarrow$ ", " $\rightarrow$ ", " $\uparrow$ ", " $\downarrow$ "keys.

To change the value of a selected item, press an "Enter" key, thereafter you can change the value by " $\uparrow$ " или " $\downarrow$ "keys. Termination of a value change is enabled by pressing "Enter".

To change a value of timer counting out, you should chose "Use" key and press an "Enter" key.

A time setting window is closed by pressing an Enter key while an Exit key is selected or by pressing an Esc key.

## 3.11.3 Testing keys

Press a "4" functional key («Test. Key.») a display for testing operation of a BUOI keyboard (figure 3.11.3). When the keys are pressed, their view on a screen is colored in a different color. To enter the Main menu an ESC. Key is held for 4 seconds.



Figure 3.11.3. Testing keys

# 4. File Transfer from BUOI into a computer

To transfer profiles which are in BUOI into hard drive of external PC the following steps are to be fulfilled (the device must be in a working position and switched on):

1. Connect BUOI to an external PC using connecting PC cable (from the accessories) through Ethernet port. Input connector of a connecting cable on a case of BUOI is shown in figure 4.1.



Figure 4.1. Input connector linking up BUOI with PC

2. Switch on PC and Search kit OKO-2 (Settings of network adapter and those of a computer Ethernet port must be the following: IP-Internet protocol address is TCP/IP 10.0.0.100, subnetwork mask is 255.255.255.0, IP-georadar address is 10.0.200.).

Warning! After switching on BUOI do not exit a device operation mode selection menu

3. Start up GeoScan32 Program and select a menu item "Special/Processing Unit"



Figure 4.2. Program GeoScan32

After activating a menu item "Processing Unit" in GeoScan32 Program window, a window "Transferring profiles from a Processing Unit" will display.



Figure 4.3. Window "Transferring profiles from a Processing Unit"

( If there is no file displayed in the window, you should disconnect BUOI from a computer, shut all radarograms in GeoScan32 program window , enter " Special" menu and click a line " Logis Settings").

4. Chose a computer directory where all the files from BUOI will be copied (figure 4.4).



Figure 4.4. Window "Transferring profiles from a Processing Unit"

Holding a "Ctrl" key, and clicking the left mouse button select files. To select one file it is enough to click the left mouse button on the sign of the required file (figure 4.5).

rofile moving from Processing B	lock	
Processing block	Computer	1
Size of disk 1023MB	Size of disk 132590MB Destination folder	Create folder
Available 974MB	Available 89060MB D:\C блока обработки\	
C51. C5 1K8 C52. C5 1K8 C53. C5 1K8 C54. C5 1K8 PRO019. GPR 246K8 PRO022. GPR PRO022. GPR	>>         PR0004 4040/8         Price           PR0005         Price         System Volume Information           PR0005         Antiautorun         Antiautorun           PR0005         Price         Price           PR0005         Price         Price           PR0007         Price         Price           PR0007         Price         Price           Price         Price         <	-
PR0003.GPR 1101KB PR0004.GPR 228KB PR0005.GPR 23476224 bytes a 5 files Remove files then coping Pefrech	The size and quantity of the selected files Heat Quintus Heat Quintus	
- Addresit		

Figure 4.5. Selected files

To start copying files press an "OK" key. After pressing "OK" key a window graphic representation of copying process will display on the screen (figure 4.6).



Figure 4.6. Copying process

After finishing a copying process a window with a corresponding message will display in the screen (figure 4.7).



Figure 4.7. Finishing a copying process

After recording files on PC you can start processing them in GeoScan32 program. For details about processing and analysis of radarogram see User Manual.

# 5. Operation with SK «Oko-2» using a notebook.

SK «Oko-2» presupposes a possibility of standard work using a notebook as an external control device along with a possibility to use all memory of notebook. You should do as follows:

- 1. Assemble SK «Oko-2» (see item 3.1 of the present manual);
- 2. Connect BUOI to a notebook with a connecting cable of PC through Ethernet port. Input connector of a connecting cable on a case of BUOI is shown in figure 4.1;

3. Pressing the button on a case of Power Unit switch on power supply of a device. At this moment a LED indicator will start flashing on a case of PU and in a few seconds after automatic testing SK "Oko-2" and a short time message «ready for work», a device operation mode selection menu will display on a screen of BUOI and a current voltage of BP too;

4. Switch on a notebook and wait for the loading of operating system;

5. Start up GeoScan32 program;

6. Further work is fulfilled according to a User Manual for GeoScan32 Program.

# 6. Requirements on safe operation and electromagnetic compatibility.

While using the device for the specified purpose (the transmitting unit of the device is switched on, about which the LED indicator on the casing of BAPP signals), one may not set the antenna units to the people. Safety of SK «Oko-2» when the standard position of the device is observed (BAPP is set to the investigated cargo and is moved along or under the surface at the distance of up to 0.1 m from the surface of the cargo) is confirmed by the conclusion of the sanitary supervision and disease control of Center for Sanitary and Epidemiological Supervision of CSSS of the Russian Ministry of Health dated 03.07.2007 r. No  $50.99.04.431.\Pi.008785.07.07$ .

- One may not sink the device or its separate parts into water or any other liquids.
- One should avoid (exclude) heavy blows and mechanical damages in running or transporting the device.
- The device does not distribute electromagnetic interference (noise) higher than a permissible noise level.(See Sanitary Certification).

# 7. Technical maintenance.

## 7.1 General instructions.

- 1. During technical maintenance some preventive maintenance is performed to maintain the proper condition of the device and to provide its normal operation within the service life (8 years).
- 2. Recommended frequency and types of technical maintenance:

3. External examination – before each running – no damages incompatible with the operation – isolation damages, cracks and so on may not be available on the case of the device and connecting cables;

4. External cleaning – once in three months – decontamination of the device and split connectors surface;

5. Battery charging PU 3,8/12 – not less than one time in 3 months-including power supply units included in tools, parts and accessories ZIP-0, working as required.

#### 7.2 Maintenance procedure

During the external examination of the device you should test the fastening BUOI, BP and BAPP to a folding handle rod, paint–and-lacquer coating condition, lack of chips and cracks on the parts made of glass-fiber material and plastic, as well as on painted parts.

Battery charging PU 3,8/12 is to be performed at reduced voltage 10.5 V, but not less than once in 3 months (including Power Unit(PU) from the accessories ZIP-0).

#### Battery charging is performed as follows:

1. Connect a power unit (PU)3,8/12 to a charging unit (CU-2);

2. Switch a power unit.

3. Switch on a charging unit to the socket 220 V 50 herz, observing the necessary measures of electrical safety;

4. Leave PU3,8/12 in such a condition for 8 - 10 hours.

The process of charging starts automatically after a connecting a charging unit to the electric mains:

First phase of battery testing comes. This phase lasts about 10seconds while the red LED on the case of a charging unit is flashing.

After finishing a test phase a process of charging PU 3.8/12 is switched on, which is indicated by a constantly gleaming. After the end of a charging process a green LED starts to flash, a red LED is not indicated, and a power unit turns to a mode of maintaining a charged status of the battery (trickle – charge). A battery is charged but it may be connected to a charging unit for unlimited time.

To preventively discharge the batteries (in order to decrease "memory effect", hold the button PRESS for 2 seconds. After the process of discharging the battery, which may last several hours, a charging process is switched on automatically.

If a red LED goes on flashing after the end of a test phase which lasts 10 seconds, and does not turn to a steady shining light, indicating a charging process that signifies that there is a malfunction of a battery and that the latter should be replaced by another one (from the accessories ZIP-0).

# 8. Routine Repair.

Routine repair is performed by a company manufacturing. To perform a routine repair a defective unit of the device is sent to a company manufacturing with a detailed description of the detected malfunctions. If the defects of the unit cannot be pin - pointed, the whole device is sent for repair.

## 9. Storage

Storage conditions of a device are to meet the requirements of GOST B9.003-80 and GOST 15150-69. A device is to be stored in storage buildings in the packing of a company manufacturing (not more than 5 packing sets may be in a pile) at the temperature of a surrounding air from +100 C up to +30°C and humidity up to 80% at temperature of 25°C. O. A group of storage conditions – 1(A).

There must not be any vapor of acids or alkali, aggressive, gases and other hazardous admixtures, causing a corrosion.

Storage time of a device before commencement of operation is not less than 5 years (without accumulator unit / rechargeable battery).

# 10. Transportation

Device transportation is performed by any transport to any distance in packing of a company manufacturing in observing the following regulations:

1. SK Oko-2 transportation must be performed in a closed transport: railway cars, containers, closed vehicles, holds without any marks of cement or chemicals transportation and so on. When transported by air the apparatus must be placed in a sealed compartment.

2. The temperature of a surrounding air during transportation must be from  $-30^{\circ}$ C up to  $+50^{\circ}$ C an the pressure from 84 до 106,7 кPa (630-800 mm of a mecury column).

3. Placing and securing of a box with a device on transport facilities must provide a steady position during transportation, lack of bias(displacement) and strikes and impacts of the devices by each other

4. Requirements of signs indicated on packing must be observed in loading and unloading.

# 11. Utilization

Accumulator batteries Ni-Mh 3,8/12B from the unit (PU)  $5\Pi 3,8/12$  are subject to utilization approved by RF State Technical Committee.

. APPENDIX №1

The sealing place







Manufacture stamp place on the pakage for the device "Zond-M"

Location of sealing







Sealing location of BAPP-II



Sealing location of BP (PU)

